RAYEN NACEF

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PROFESSIONAL EXPERIENCE

AI Research Internship - Mila, Polytechnic Montreal, Canada - MITACS Program J

Jul - Sep. 2025

Pioneered token-level credit assignment in GRPO- λ paper, boosted LLM reasoning accuracy by 18%, and contributed to training pipelines, dataset preprocessing, and reinforcement learning techniques for reasoning tasks.

Key words: LLM, RL, Python, Pytorch Transformers, HPC, Reasoning, Github, Slurm, Linux Bash

End of Study Internship - Proxiad GitHub Link

Feb - Mai. 2025

Built an e-commerce chatbot to track orders and handle claims, implemented data preprocessing pipelines, dynamic knowledge base integration, and fine-tuned models for natural language interaction with role-based access.

Key words: LLM, RAG, FastAPI, Spring Boot, Angular, Python, Java, Docker, Kubernetes, Gitlab, Keycloak

Summer Internship - Focus Corporation Github Link

Jul - Aug. 2024

Developed an LLM-powered digital assistant for the automotive industry for responsive interaction and Wireshark-based network diagnostics.

Key words: LLM, NLP, RAG, Data preprocessing, DL, GenIA, Python, HF, Docker, Prompt Engineering, Ollama

PROJECTS

CryptoFacial Recognition

Dec - Jan. 2025

Developed a real-time facial recognition system with OpenCV and the face recognition library, integrated with secure AES encryption for communication between a client (PC) and an embedded device (ESP32).

Key Words: Python, ESP32, TCP Socket, Face recognition, AES, OpenCV

FreeRTOS-Based Real-Time Robot Control System

Oct - Nov. 2024

Designed and implemented a multitasking system for a remotely controlled robot, featured a real-time motor control and battery monitoring via a TCP-based server.

Key Words: C++, FreeRTOS, ESP32, TCP/IP, multitasking, GPIO, ADC, embedded systems

Intelligent Intrusion Detection for CPS Github Link

May - Jul. 2024

Implemented four machine learning algorithms for intrusion detection, reduced false positives by 30% and enhanced detection accuracy.

Key Words: Machine Learning, Scikit-learn, TensorFlow, Keras, Python

HexaSwift Robot Feb - April. 2024

Designed and developed an autonomous hexapod robot for indoor navogation with mobile app integration, combining robotics and AI for improved indoor navigation.

Key Words: OpenCV, Raspberry Pi, Embedded C, PID, ArUco Markers, Arduino, UART, Python

EDUCATION

ENSI - Computer Science Engennering diploma

2022 - 2025

IPEIT - Preparatory Cycle for Engineering Studies in Physics and Chemistry, DEUPC diploma

2020 - 2022

SKILLS

Programming Languages: Python, C, C++, Java

AI Area: ML, DL, GenAI, Computer Vision, RL, LLM, NLP

Hardware Environments: ESP32, STM32, Raspberry pi

Tools: PlatformIO, STM32 Cube IDE, VS Code, Git ,GitHub, Keil, Intellij Idea

Platforms: Windows, Linux

DevOps Tools: Docker, Kubernetes, Gitlab, CI/CD

Database: PostgresSQL, SQL, Redis

Soft Skills: Reaserch Writting, Time Management, Team Work, Quick Learner

Languages: English, French, Arabic